User Manual

Mars-F1000 Series

Applicable Models: Mars-F1000/1011/1022/1200/1211/1222

Date: September 2021
Doc Version: 1.1
English

Thank you for choosing our product. Please read the instructions carefully before operation. Follow these instructions to ensure that the product is functioning properly. The images shown in this manual are for illustrative purposes only.

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If there is any issue related to the product, please contact us.

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To know more about our global branches, visit www.zkteco.com.
About the Company

ZKTeco is one of the world’s largest manufacturer of RFID and Biometric (Fingerprint, Facial, Finger-vein) readers. Product offerings include Access Control readers and panels, Near & Far-range Facial Recognition Cameras, Elevator/floor access controllers, Turnstiles, License Plate Recognition (LPR) gate controllers and Consumer products including battery-operated fingerprint and face-reader Door Locks. Our security solutions are multi-lingual and localized in over 18 different languages. At the ZKTeco state-of-the-art 700,000 square foot ISO9001-certified manufacturing facility, we control manufacturing, product design, component assembly, and logistics/shipping, all under one roof.

The founders of ZKTeco have been determined for independent research and development of biometric verification procedures and the productization of biometric verification SDK, which was initially widely applied in PC security and identity authentication fields. With the continuous enhancement of the development and plenty of market applications, the team has gradually constructed an identity authentication ecosystem and smart security ecosystem, which are based on biometric verification techniques. With years of experience in the industrialization of biometric verifications, ZKTeco was officially established in 2007 and now has been one of the globally leading enterprises in the biometric verification industry owning various patents and being selected as the National High-tech Enterprise for 6 consecutive years. Its products are protected by intellectual property rights.

About the Manual

This manual introduces the operations of Mars-F1000 Series.

All figures displayed are for illustration purposes only. Figures in this manual may not be exactly consistent with the actual products.

Features and parameters with ★ are not available in all devices.
Document Conventions

Conventions used in this manual are listed below:

GUI Conventions

<table>
<thead>
<tr>
<th>Convention</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Bold font</strong></td>
<td>Used to identify software interface names e.g. OK, Confirm, Cancel.</td>
</tr>
<tr>
<td>&gt;</td>
<td>Multi-level menus are separated by these brackets. For example, File &gt; Create &gt; Folder.</td>
</tr>
</tbody>
</table>

| **For Device** | |
| **Convention** | **Description** |
| < > | Button or key names for devices. For example, press <OK>. |
| [ ] | Window names, menu items, data table, and field names are inside square brackets. For example, pop up the [New User] window. |
| / | Multi-level menus are separated by forwarding slashes. For example, [File/Create/Folder]. |

Symbols

<table>
<thead>
<tr>
<th>Convention</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>📝</td>
<td>This represents a note that needs to pay more attention to.</td>
</tr>
<tr>
<td>☑️</td>
<td>The general information which helps in performing the operations faster.</td>
</tr>
<tr>
<td>⭐️</td>
<td>The information which is significant.</td>
</tr>
<tr>
<td>🚫</td>
<td>Care taken to avoid danger or mistakes.</td>
</tr>
<tr>
<td>🚨</td>
<td>The statement or event that warns of something or that serves as a cautionary example.</td>
</tr>
</tbody>
</table>
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1 Overview

The Mars-F1000 Series flap barrier is an elegant cost-effective entrance control system designed for high-traffic volume. The Mars-F1000 Series Flap Barrier are normally held in a locked position, thus denying access to the secured side. When the Mars-F1000 Series correctly identifies the user’s Card (RFID)/Fingerprint/QR code, etc. to verify the identity, and the barrier opens to allow the pedestrians to pass by.

1.1 Chassis Design and Dimensions

The device has a stainless steel (Mars series) and cold rolled steel (Mars Pro series) plate stamp form that makes it anti-rust and durable. The Acrylic panel provides simple and beautiful design with corrosion protection. It provides orderly and civilized passage to the persons and restricts illegal personnel access. In case of emergencies, it ensures that evacuation passage runs smoothly and is convenient for personnel.
Mars-F1000’s appearance and dimensions are shown below:

1.2 Mechanical System

The mechanical system of the flap barrier includes the chassis and the core component. The chassis is a carrier where the Direction indicator, Reader, QR code scanner, Fingerprint sensor, Infrared sensor, and the Door lock are installed. The core component mainly consists of the Motor, Frame, Bearing, and swing Arm.

1.3 Electronic Control System

The electronic control system of a flap barrier is mainly composed of the Card Reader/Fingerprint sensor/QR code, Flap Barrier control board, Infrared Sensor, Direction Indicator and Alarm.

**Reader**: The reader reads the data in the card and sends it to the Access Controller.

**Fingerprint sensor**: The device compares the fingerprint that is being pressed onto the fingerprint sensor with all the fingerprint data and sends it to the Access Controller.

**QR code sensor**: The sensor compares the acquired QR code with all QR code data registered in the device and sends it to the Access Controller.

**Flap barrier control board**: The flap barrier control board is the system’s control center that receives signals from the reader and the photoelectric switch performs logical calculation and processing of these signals and sends executive commands to the Direction indicator, electric motor and the alarm.
**Infrared Sensor:** It detects the position of the pedestrian and plays the role of safety protection.

**Direction Indicator:** This indicator displays the pedestrian passage path and directs them to pass through the lane in a safe and orderly manner.

**Alarm:** The alarm gives an alarm voice if the system detects any unauthorized entry to the passage.

### 1.4 Working Principle

1. After powering on to the device, the system performs the Power-On Self-Test.

2. When a valid Card/Fingerprint/QR code is detected, the buzzer will give a positive audible prompt to the pedestrian, indicating that successfully verified. And then, the reader sends signals to the Access Controller to request permission to pass through the passage. The Access Controller will send the signal to the master control panel.

3. After receiving the signal from the Access Controller, the flap barrier control board sends valid control signals to the direction indicator and the electric motor. At last the direction arrow turns green.

4. Pedestrians passes through the passage according to the direction indicator signs. Infrared sensors keep on detecting the pedestrian during the whole process, and continue to send signal to the master control board until the pedestrian passes completely through the passage.

5. If the pedestrian enters the passage but forgets to verify identification, or if the card held/fingerprint/QR code by the pedestrian is invalid, the system will prompt an audible alarm to stop and retreat the pedestrian from the passage. The pedestrian can pass through the passage only after a valid card/fingerprint/QR code is successfully verified.

### 1.5 System Composition

The single-lane management system is composed of two single-core swing barriers. The multi-lane management system is composed of two single-core barriers and multiple dual-core barriers.

**Working modes of the system**

To make the product more versatile, this system provides multiple working modes for the user, including Normal working mode, Normally open mode, Normally close mode and Testing mode.

**Normal Working Mode:** In this working mode, the flap barrier works normally.

**Normal Open Mode:** In this working mode, the flap barrier is always open.

**Normal Close Mode:** In this working mode, the flap barrier is always closed.

**Testing Mode:** In this working mode, the flap barrier performs auto-test.
## 1.6 Technical Specifications

<table>
<thead>
<tr>
<th>Feature</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Communication</td>
<td>TCP/IP, RS485, 4G/WIFI</td>
</tr>
<tr>
<td>Input Voltage</td>
<td>AC110V to 220V, 50 Hz to 60Hz</td>
</tr>
<tr>
<td>Input Control Signal</td>
<td>Switching Signal</td>
</tr>
<tr>
<td>Output Voltage</td>
<td>DC 24V</td>
</tr>
<tr>
<td>Protection Level</td>
<td>IP34</td>
</tr>
<tr>
<td>Time of Gate Opening/Closing</td>
<td>Minimum 0.8 Seconds</td>
</tr>
<tr>
<td>Relative Humidity</td>
<td>&lt;95% (Non-condensing)</td>
</tr>
<tr>
<td>Temperature</td>
<td>-25°C to 65°C (Standard)</td>
</tr>
<tr>
<td></td>
<td>-40°C to 80°C (Optional)</td>
</tr>
<tr>
<td>Throughput Rate</td>
<td>Maximum 30 persons/minute</td>
</tr>
<tr>
<td>Motor</td>
<td>Brushless Motor</td>
</tr>
<tr>
<td>Infrared Sensors</td>
<td>16 Pairs</td>
</tr>
<tr>
<td>Working Environment</td>
<td>Indoor/Outdoor (if sheltered)</td>
</tr>
<tr>
<td>Dimension (mm) (L<em>W</em>H)</td>
<td>1355* 180*1010</td>
</tr>
<tr>
<td>Noise</td>
<td>&lt;60dB</td>
</tr>
<tr>
<td>Certifications</td>
<td>CE, FCC</td>
</tr>
</tbody>
</table>
1.7 Anti-collision Force Parameters

The swing arm can withstand shaking of 400N.

⚠️ The picture only shows the anti-collision level, please do not damage the device.
2  Function Introduction

2.1  Fingerprint Verification

In this verification mode, the device compares the fingerprint that is being pressed onto the fingerprint reader with all the fingerprint dat and sends it to the Access Controller.

The device enters the fingerprint authentication mode when a user presses his/her finger onto the fingerprint scanner.

**Recommended fingers:** It is recommended to use index, middle, or ring finger for registration and avoid using the thumb or little finger, as they are difficult to accurately press onto the fingerprint reader.

![Fingerprint Example](image-url)

Too low  Too close to the edge

Vertical
**Note:** Please use the correct method when pressing your fingers onto the fingerprint reader for registration and identification. Our company will assume no liability for recognition issues that may result from incorrect usage of the product. We reserve the right of final interpretation and modification concerning this point.

### 2.2 Card Verification

The Card Verification mode compares the card number in the card induction area with all the card number data registered in the device and sends it to the Access Controller.

The device enters the card authentication mode when a user presses his/her card to the card reading area.
2.3 QR code Verification

The QR code Verification mode is to scan the QR code on the user's mobile phone through the QR code scanner and compare the data with the registered QR code, and then sends it to the Access Controller.

When the user places the mobile phone displaying with the QR code on top of the QR code scanner, the device enters the QR code authentication mode.
2.4 Facial Verification

In this verification mode, the device compares the collected facial images with all face data registered in the device and then sends it to the Access Controller.

Try to keep the face in the centre of the screen during authentication. Please face towards the camera and stay still during face registration.

Recommended Standing Posture and Facial Expression:

Note: Please keep your facial expression and standing posture natural while enrollment or verification.
Installation on the barrier gate:

1. Please pass the wire through the bracket before installation.
2. Insert the bracket into the hole and fix it with a nut.
3. Adjust the angle of the device.
2.5 Wireless Remote Control★

The wireless remote control of flap barrier is an intelligent device that remote controls the entrance and exit. It is designed for manual control of the flap barrier by the administrator. The wireless remote control has four buttons A, B, C, and D, corresponding to the options open entrance gate, open exit gate, emergency mode open-bar pass, and alarm lock.

<table>
<thead>
<tr>
<th>Buttons</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>Press the button once to open the flap barrier on the entrance and can pass by verification from the entrance.</td>
</tr>
<tr>
<td>B</td>
<td>Press the button once to open the flap barrier on the exit and can pass by verification from the exit.</td>
</tr>
<tr>
<td>C</td>
<td>In emergency mode, press the button once to open the gate. Then the entrance and exit sides gate open and can pass freely without verification.</td>
</tr>
<tr>
<td>D</td>
<td>Press the button once to close the gate. Then the entrance and exit sides are controlled by the flap barrier. The verification becomes invalid, and no pass is allowed.</td>
</tr>
</tbody>
</table>
3 Menu Introduction

There are 4 keys on the control panel, "MENU", "MODE", "ADD" and "DEC".

**MENU:** It is used for enter the Settings menu and to confirm the current modified value.

**MODE:** It is used to go back to the previous menu and discard the current operation.

**ADD:** It is used for navigating to the upper menu item and increasing the value.

**DEC:** It is used for navigating to the lower menu item and decreasing the value.

### Display Mode (01EXXX)
- (01E000) Displays current position of the gate. (Default)
- (01E001) Infrared input signal.
- (01E002) Controls input signal.
- (01E003) Test mode (the digital LED displays "---" in the test mode).
- (01E004) Version number.

### Master/Slave Turnstile Setting (02EXXX)
- (02E000) Master turnstile
- (02E001) Slave turnstile (Default)
**Access Mode Setting (03EXXX)**

Two-way control (Default)

- In control, out free
- In free, out control
- In control, out forbidden

Two-way free

- In forbidden, out control
**Automatic Closing Time for Unmanned Passage (04EXXX)**
Verify that no one passes after the switch is opened. After arriving at the set time, the switch will shut down automatically. The valid value for Automatic Closing Time for Unmanned Passage can be set between 2 to 60s and the default value is 5s.

**Opening Speed (05EXXX)**
Set the Opening Speed to open the gate. The smaller the number is set, the faster the speed. The Opening Speed value can be set between 1 to 5 seconds and the default value is 3s.
**Opening Brake Stroke (06EXXX)**
The larger the number is set, the larger the deceleration stroke. The Opening Brake Stroke value can be set between 10 to 25 seconds and the default value is 16.

**Closing Speed (07EXXX)**
Set the Closing Speed to close the gate. The smaller the number is set, the faster the speed. The Closing Speed value can be set between 1 to 5 seconds and the default value is 3s.

**Closing Brake Stroke (08EXXX)**
The larger the number is set, the larger the deceleration stroke. The Closing Brake Stroke value can be set between 10 to 25 seconds and the default value is 16.

**Memory Function (09EXXX)**
- (09E001) Close memory function (Default)
- (09E002) Open memory function

When more than two legal access signals are given at the same time (including the same direction and the opposite direction), the system will remember all the pass requests and complete each pass in turn.

**Closing Delay after Passing (10EXXX)**
Set the delay time of gate closing after passing. The valid value for Gate Closing Delay Time can be set between 0 to 60s and the default value is 0s.
False Direction Entry (11EXXX)
- (11E000) Close gate
- (11E001) Alarm (Default)
- (11E002) Turn off this function

Anti-tailgate Setting (12EXXX)
- (12E000) Close gate
- (12E001) Alarm (Default)
- (12E002) Turn off this function
Fire Mode (13EXXX)

- (13E000) Entry opening (Default)
- (13E001) Exit opening
- (13E002) Close fire mode

Voice Volume Adjustment (14EXXX)

Adjust the volume of the device, the larger the number is set, the louder the volume. The valid value for Volume Setting can be set between 0 to 30 and the default value is 8.

Close Alarm Sound (15EXXX)

- (15E001) Close
- (15E002) Open (Default)

When the alarm sound is turned off, the Turnstile will not emit an alarm sound when encountering an alarm situation.

Exchange Entrance and Exit Voice (16EXXX)

- (16E000) Right in, left out (Default)
- (16E001) Right out, left in

Ordinary alarm sounds do not need to be exchanged.

Verification Mode (17EXXX)

The verification mode can be set as Allow to verify in channel, or Forbid to verify in channel.
Allow to verify in channel (Default)  

Forbid to verify in channel

**Closing Position (18EXXX)**

- (18E000) Close the gate after pedestrians pass the last pair of infrared sensors (Default)
- (18E001) Close the gate after pedestrians pass the penultimate pair of infrared sensors

When the anti-pin area is set to 1, pass the penultimate pair of infrared sensors is effective.

**Motor Installation Direction (19EXXX)**

- (19E000) AA movement (Default)
- (19E001) AB movement
- (19E002) BA movement
- (19E003) BB movement

**Stay Duration Time (20EXXX)**

Set the duration of stay in the channel after successful verification, the valid value for Stay Duration Time can be set between 5 to 30s and the default value is 10s.
Voice Switching (21EXXX)

- (21E001) Alarm (Default)

Restore Factory Settings (22EXXX)

- (22E000) Normal work (Default)
- (22E001) Restore factory settings
4 Wiring Diagram
## Packing List

The package consists of the following items:

<table>
<thead>
<tr>
<th>Item</th>
<th>Quantity</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mars-F1000</td>
<td>1 (master and slave)</td>
</tr>
<tr>
<td>Power cable</td>
<td>1</td>
</tr>
<tr>
<td>Card</td>
<td>1</td>
</tr>
<tr>
<td>Expansion Screw M12*100</td>
<td>8</td>
</tr>
</tbody>
</table>
6 Maintenance

6.1 Chassis Maintenance

The chassis is made up of stainless steel or cold rolled. If it is used for substantial period, then there may be rust stains on its surface. Regularly clean the surface with a clean cloth carefully. Coat the surface with anti-rust oil and do not cover the infrared sensor.

6.2 Movement Maintenance

Switch off the power supply before maintenance. Open the door, clean surface dust, and apply lubricant for smooth movement.

6.3 Power Supply Maintenance

- Switch off the power supply before maintenance.
- Check the power plug connection, if found loose, fix it properly.
- Do not change any connection position randomly.
- Check the external power supply insulation periodically.
- Do periodic check for any kind of leakage.
- Check if the technical parameters of interface are normal.
- Check the service life of the electronic components and replace accordingly.

**Caution:** All the above-mentioned maintenance methods for swing barrier must be carried out by a professional technician, especially the movement and the electric control part. For ensuring operational safety, first switch off the power supply when the barrier is not in use.
# Troubleshooting

<table>
<thead>
<tr>
<th>No.</th>
<th>Failure Description</th>
<th>Cause</th>
<th>Solution</th>
</tr>
</thead>
</table>
| 1   | No response from direction indicator or indication is not correct. | **Cause:** It may be due to the incorrect connection of indicator.  
**Solution:** Check whether the connection of the indicator is correct or not. | |
| 2   | After swiping the card, there exists only swing arm action. | **Cause:** It may be due to the existing any problem in the master and slave machine type setting.  
**Solution:** Check the master and slave machine type setting and the 5-core, 2-core connection line. | |
| 3   | Delay in barrier opening or it doesn’t close. | **Cause:** It may be due to the time of the barrier opening is set as too long.  
**Solution:** Check whether the time of the opening is too long, or the IR sensor is covered. | |
| 4   | Motor doesn’t rotate, the resistance is much, or the bearing is loose. | **Cause:** It may be due to the motor’s rotation angle is not set properly.  
**Solution:** The motor works properly, but the rotated angle is not sufficient, so it may cause loosening of bearing. | |
| 5   | When powered ON, the swing doesn’t return to the initial position. | **Cause:** It may be due to the obstacle that lies in the sensing area.  
**Solution:** Ensure that no obstacle is in the sensing area, then restart the equipment. | |